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TM1638 quick reference sheet

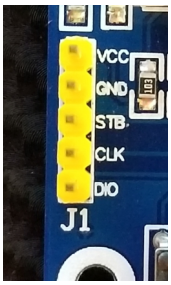
These instructions should also be applicable to the TM1637 and TM1639 LED driver chips

Board Pinouts:

Vcc: +5V or +3.3V. 3.3V should work on boards with red or green LED’s

GND: Ground, 0 volts

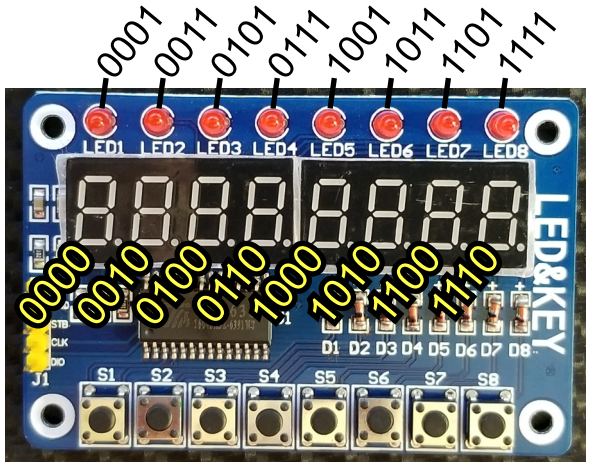
DIO: Digital Input/Output. Bi-directional data line, receiving data for the displays & LED’s or sending data read from the keys. Data direction is set by instructions. **NOTE:** when reading data from the DIO pin, the datasheet recommends using a pullup resistor of 10k on the DIO line. If using a microcontroller such as PIC or Arduino, just simply use its internal pullup resistors (i.e. the INPUT_PULLUP instruction with Arduino).



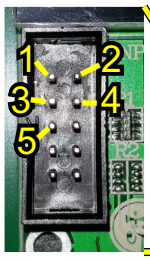
CLK: Clock. As the next bit of data is held on the DIO line, the CLK line is pulsed to commit that data bit to the internal shift registers. Or if data is being output on DIO, a CLK pulse causes the data line to be loaded with the next data bit from the keypad shift registers.

STB or STRB: Strobe. When strobe goes low, the controller chip starts listening to the DIO line, expecting an instruction or data. Because an instruction can be followed by multiple bytes of data, strobe is set high upon completion of all instruction and data transmissions. **NOTE:** Some boards (like the bicolour LED board shown below) have multiple strobe lines. Simply use STRB0 for your strobe line.

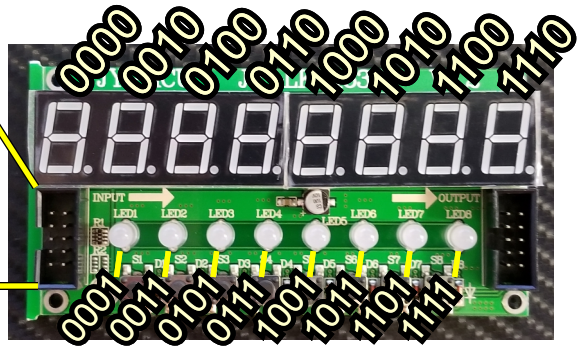
7 segment display & LED addressing:



Addresses shown are the lower nibble required for display instructions. The upper nibble sets the addressing mode, the lower nibble dictates where the data byte should go.

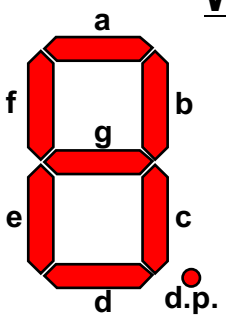


Pins:
1: Vcc
2: GND
3: CLK
4: DIO
5: STRB0



On boards with bi-coloured LED’s, the addressing is exactly the same, though the board layout may be different.

Writing to the 7 segment displays



7 segment display control byte

d.p.	g	f	e	d	c	b	a

To illuminate a particular segment in the display, simply send a 1 to the segment's corresponding bit in the display's control byte.

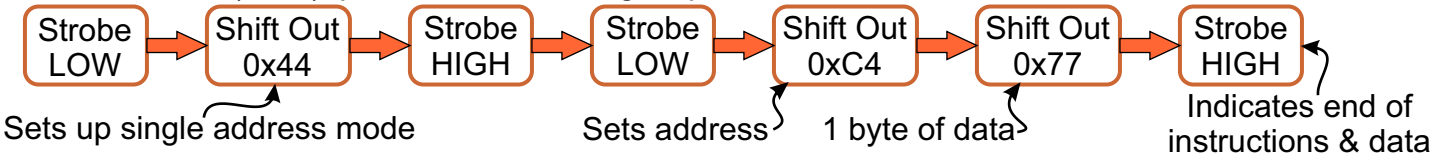
Example 7 segment characters:

8.	0111 0111 0x77	8.	0101 1011 0x5B	8.	1111 1111 0xFF
8.	0000 0110 0x06	8.	0101 1110 0x5E	8.	0000 0111 0x07
8.	1011 1111 0xBF	8.	0111 1100 0x7C	8.	0100 1001 0x49
8.	0011 1111 0x3F	8.	0011 1110 0x3E	8.	0100 0000 0x40
8.	0110 0110 0x66	8.	0111 1101 0x7D	8.	0111 0110 0x76

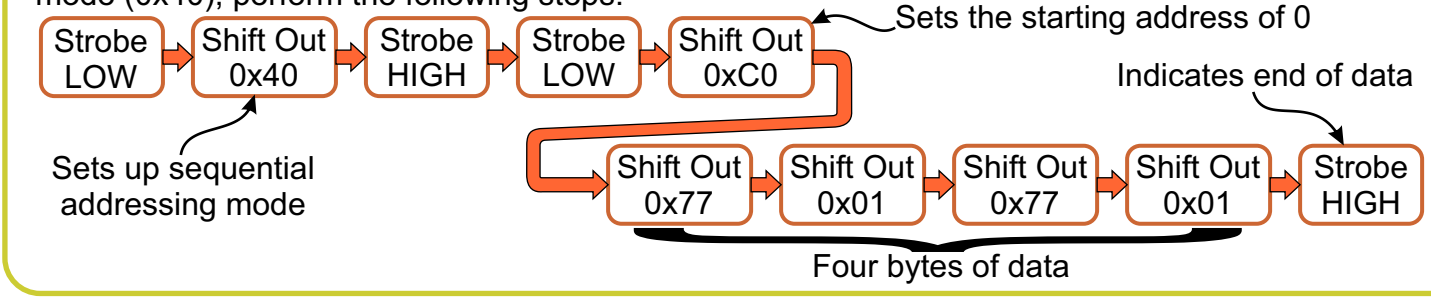
Sending instructions and data

Instruction	Details on its use
0x8? 1000 obbb	Turn display on or off (bit o) and set brightness (bbb bits) **Example:** To turn on display and set full brightness would be 1000 1111 or
0x44 0100 0100	Sets up single address mode to write to a single address.
0x40 0100 0000	Sets up sequential address mode.
0xC? 1100 aaaa	This instruction follows one of the addressing commands and sets the address (lower four bits, aaaa) that you wish to write to. **Example:** Sending 0x57 to address 0x02 in single address mode, you send the instruction 0x44, then 0xC2 (0xC combined with the address of 2 as the lower nibble), and then followed up by the data byte 0x57. See examples below.
0x42 0100 0010	Read the buttons. Once the instruction is received, the controller will set the DIO line as an output and will send 4 bytes of data. See page 3 for details on using this instruction and retrieving the data.

Example 1: To put a capital A (0x77) on the 3rd 7 segment display (address 0100, or 4), in single address mode (0x44), perform the following steps:

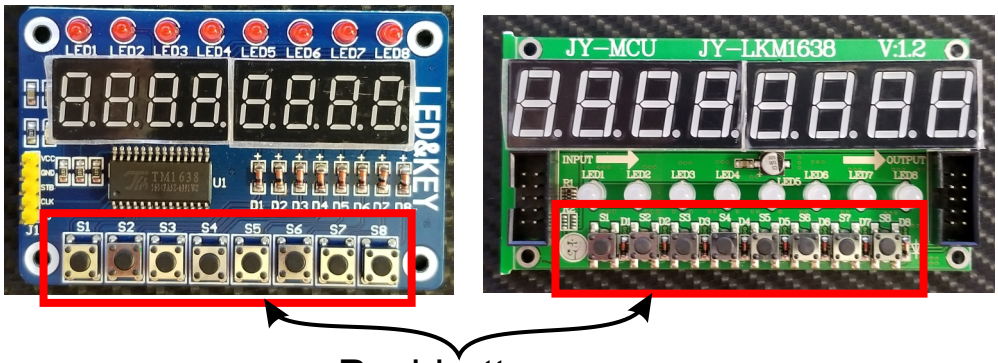


Example 2: To put a capital A (0x77) on the 1st and 2nd 7 segment display (hex address 0 and 2), *and* turn on discrete LED's 1 & 2 (setting bit 0 at addresses 1 and 3) in sequential address mode (0x40), perform the following steps:



Reading the pushbuttons

The TM1638 controller chip can multiplex up to 16 pushbuttons in four rows. How many pushbuttons there are on a particular circuit board, and how the TM1638 is wired to those pushbuttons is decided by the board manufacturer. The controller chip reads four rows of pushbuttons and thus returns four bytes of data over the DIO line. In the case of the two boards shown, the pushbuttons (marked S1 through S8 on both boards) return values on the individual bytes as show in the chart below:



bit	7	6	5	4	3	2	1	0
Byte 0	X	X	X	S5	X	X	X	S1
Byte 1	X	X	X	S6	X	X	X	S2
Byte 2	X	X	X	S7	X	X	X	S3
Byte 3	X	X	X	S8	X	X	X	S4

X= null return. These bits will always return a 0 because they're not hooked up to anything

Examples: If the user is pressing button S7 only, byte 2 will return decimal 16 (0x10), all other bytes will return 0. If user is pressing buttons S2 and S6, byte 2 will return decimal 17 (0x11), all other bytes will return 0. If user is pressing buttons S8 and S3, byte3 will return decimal 16 (0x10) and byte 2 will return decimal 1 (0x01), all other bytes will return 0. Pressing S1 will return decimal 1 (0x01) on byte 0, all other bytes will read 0.

Reading the pushbutton registers: After sending the instruction to read the pushbutton registers, the controller will switch the DIO line to output and transmit 4 bytes of data in the usual shift out fashion. The microcontroller needs to switch data direction on the pin it has connected to the board's DIO line after sending the instruction. Perform the following steps: